

# **TABLE OF CONTENTS**

# Introduction

**F8 Device Descriptions** 

3850 Central Processing Unit

3851 Program Storage Unit

3853 Dynamic Memory Interface

3852 Static Memory Interface

3854 Direct Memory Access

**F8 Application Spectrum** 

**F8 Customer Support** 

**F8 Instruction Set Summary** 

**F8 Power Requirements** 

F8 Signal Electrical Specifications

# THINK F8 UNIVERSAL STANDARD MICROPROCESSOR

### VERSATILE .. EFFICIENT .. COST EFFECTIVE

The ultimate goal, from F8 design concept through development and production, was to produce the most versatile, efficient, cost-effective microprocessor system available today. To accomplish this, five stringent parameters, based on user experience with other systems, were set forth as guidelines for the F8.

- Minimum Parts Count
- Cost Effectiveness
- Simple Peripheral Interfaces
- Easy Expansion through Modular Architecture
- Simplified Programming and Debugging

# HOW WERE F8 GOALS MET?

By . . . unique system partitioning the system functions have been divided among the various circuits of the F8 family to provide sophisticated modularity. As a result, it is now possible to build a minimum microprocessor system with only two devices. To this system PSU, RAM and I/O devices can be added to form medium size or memory intensive systems with a minimum use of external parts. And, finally, for

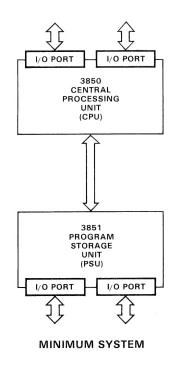
solving complex problems, the F8 devices can be connected as subsystems into a synergistic system of independent microprocessors.

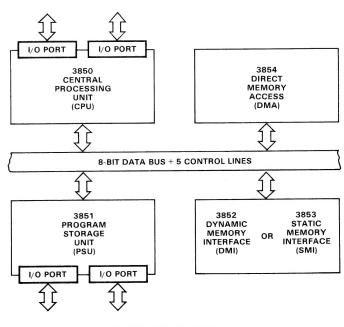
By . . . incorporating the I/O structure on the chips so that the majority (95%) of the peripheral devices can be directly controlled without the need for special circuits. The trick is to accommodate the characteristics of a given peripheral device in the software. The I/O hardware structure includes a programmable timer, an efficient interrupt system and bidirectional I/O ports.

By . . . providing *carefully thought out software* for generating and debugging microprograms and a choice of three hardware modules for speeding up prototype development.

# WHAT IS THE RESULT?

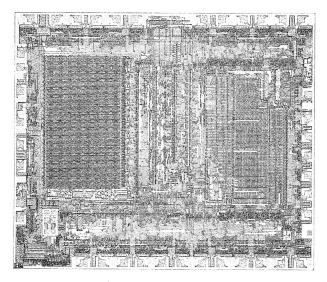
. . . a complete family of LSI circuits that can be used as building blocks to construct versatile, efficient, cost effective systems from the most simple to the highly complex.



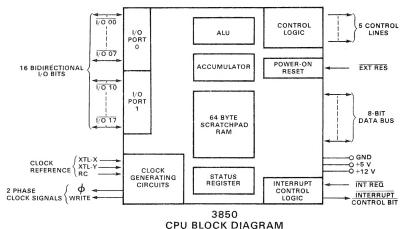


**F8 DEVICE FAMILY** 

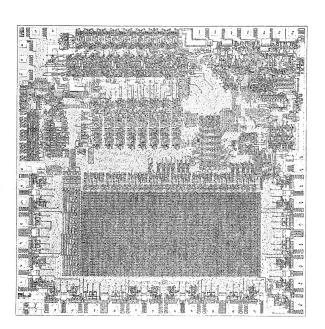
# 3850 CENTRAL PROCESSING UNIT



Fairchild's F8 Central Processing Unit (CPU) contains all of the functions of an ordinary central processor and adds some time and money saving features uniquely its own. For instance, the 64 bytes of scratchpad RAM memory already included on the F8 CPU eliminate the need for external RAM circuits in many applications. Clock and power-on-reset circuitry, normally requiring additional integrated circuit packages, are included on-chip. Fairchild's CPU also contains 16 bits of fully bidirectional input and output lines internally latched (for storing output data) and capable of driving a standard TTL load.

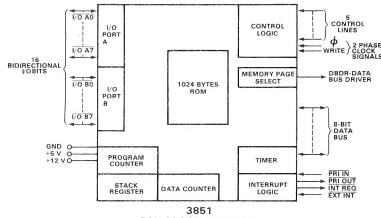


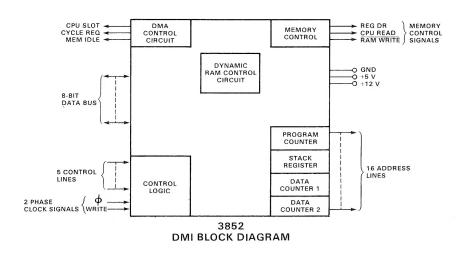
# 3851 PROGRAM STORAGE UNIT

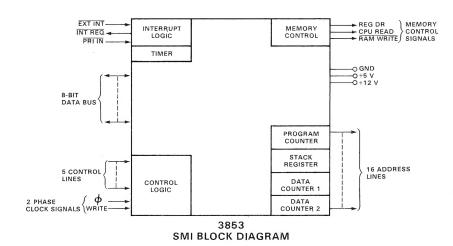


It is important to note that Fairchild's Program Storage Unit (PSU) is not just a conventional Read Only Memory. In addition to containing 1024 bytes of mask programmable ROM for program and constant storage, the F8 PSU includes the addressing logic for memory referencing, a Program Counter, an Indirect Address Register (the Data Counter) and a Stack Register. A complete vectored interrupt level, including an external interrupt line to alert the central processor, is provided. All of the logic necessary to request, acknowledge and reset the interrupt is on the F8 PSU. The 8-bit Programmable Timer is especially useful for generating real time delays. The PSU has an additional 16 bits of TTL compatible, bidirectional, fully latched I/O lines.

Systems requiring more program storage may be expanded by adding more PSU circuits. For example, one F8 CPU and three F8 PSUs will produce a microprocessor system complete with 64 bytes of RAM, 3072 bytes of ROM, 64 I/O bits, three interrupt levels, and three programmable timers. This complete system will require only four IC packages.



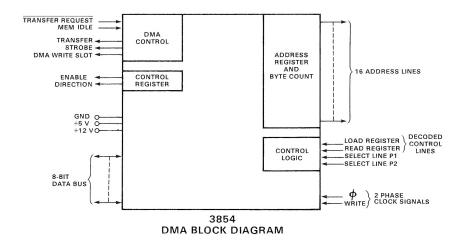




# 3852/3853 MEMORY INTERFACE

For applications requiring more than the 64 byte RAM located on the CPU, two memory interface circuits are included in the F8 set. Each device generates the 16 address lines and the signals necessary to interface with up to 65K bytes of RAM, PROM or ROM memory. Either device may be used in conjunction with standard static semiconductor memory devices.

The Static Memory Interface (SMI) contains a full level of interrupt capability and a programmable timer. The Dynamic Memory Interface (DMI) contains all of the logic necessary to refresh MOS dynamic memories without degrading the system throughput time. The F8 DMI can also interface with static memories when desired.



# 3854 DIRECT MEMORY ACCESS

Fairchild's Direct Memory Access (DMA) device sets up a high speed data path to link F8 memory with peripheral electronics. The F8 DMA circuit, when working in conjunction with the F8 DMI, does not require overhead electronics to keep track of memory addresses, bytes transferred and handshaking signals. The data transfer is initiated by the CPU under program control. Once started, the DMA transfer will continue without CPU intervention. The CPU can sense the enable line of the DMA to determine the completion of a transfer. The entire DMA transfer will take place without halting the central processor.

# F8 MICROPROCESSOR APPLICATION SPECTRUM

Because of its unique system partitioning, the F8 device set can be applied across a wide range of applications. The minimum two-circuit system is the basis for a modular architecture that can handle increasingly complex problems. A system of medium complexity can be designed by adding more F8 PSUs. The use of an F8 memory interface device allows up to 65K bytes of standard memories to be incorporated into the F8 system. For highly complex applications, independent F8 subsystems can be connected into a multiprocessing system in which each subsystem can operate independently yet can be controlled by one CPU that is the coordinator.



**AUTOMOTIVE IGNITION CONTROL AUTOMOTIVE BRAKES** AUTOMOTIVE DASH CONTROL HOME APPLIANCES **VENDING MACHINES ELECTRONIC SCALES** SPECIALTY CALCULATORS **ELECTRONIC GAMES AUTOMATED GAS PUMPS** FAST FOOD CASH REGISTERS PAPER TAPE HANDLERS CASSETTE TAPE HANDLERS CASH REGISTERS **COMMUNICATION LINE** CONTROLLERS PRINTER CONTROLLERS TRAFFIC LIGHT CONTROLLERS **COPIERS PABX** FILM PROCESSING **AUTOMOTIVE ANALYZERS** FLOPPY DISK CONTROLLERS MESSAGE CONCENTRATORS MEDICAL INSTRUMENTS MACHINE TOOL CONTROL STORAGE AND FORWARD MESSAGE SWITCHING ADAPTIVE EQUALIZERS

**FAST FOURIER TRANSFORM** 

**ANALYZERS** 

CUSTOM

SENSITIVE

PERFORMANCE

MINICOMPUTER

OR BIT-SLICE STRUCTURE

SENSITIVE

#### A TWO-CIRCUIT SYSTEM

The two-circuit F8 microprocessor is suitable for small data terminals, controllers, and specialty calculators. The keyboard is connected directly to the F8 I/O ports without special interfaces. Switch-bounce protection, rollover, and key encoding are all under software control. Software also decodes signals for LED readouts.

As an appliance controller, for example, the two-circuit system can perform all input-output sensing, actuating, timing, and computation operations. A system like the combination washing-machine-and-dryer controller in *Figure 1* requires more than 250 components when other microprocessor device sets are used, but with the F8 devices uses only 55 components, including 28 LEDs and the power semiconductor devices and relays used to control the motors. A set of custom circuits would also require about 50 parts, but initial engineering expense is heavy and severe penalties are incurred if changes are required. With the F8 system changes can be made by merely changing the program.

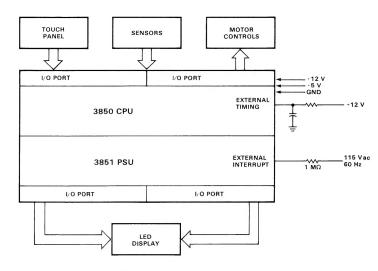


Fig. 1. Two-Circuit System

#### A MORE COMPLEX SYSTEM

The versatility of the F8 system is indicated by the traffic-light-controls system in *Figure 2*. The use of one CPU and two PSU circuits provides the designer with two timers, two interrupts, an onboard clock, onboard power-on reset, onboard switch decoding, and 48 bidirectional I/O bits. This system could be tied to vehicle detectors in the road, to monitor traffic for left-turn lanes as well as through-traffic flow in four directions. It would also react to interrupts from the pedestrian control buttons at each corner. There also is sufficient I/O capability to permit communication with and control of neighboring intersections and to allow the system to be operated manually or tested for proper operation.

Five F8 features are of particular interest for this type of application. One of the interrupts can eliminate the need for

such external circuits as a comparator to compare a count of the cars with a predetermined value to cause the light to change. (The CPU can handle the simple arithmetic of counting cars.) This interrupt also eliminates the need for continuous polling of traffic count by the microcomputer. The second interrupt would be ideal for permitting pedestrian control to override the automatic system. The internal clock, with an external cyrstal, can also control light routines.

The two timers permit simultaneous counting of delay for vehicle signals and flashing warning lights for pedestrians. The onboard power-on reset acts in case of power failure to start the system automatically when power is renewed. The bidirectional I/Os have built-in latches that eliminate the need for external latches for the job of "holding" commands for lights as well as the momentary commands provided by timers and sensors.

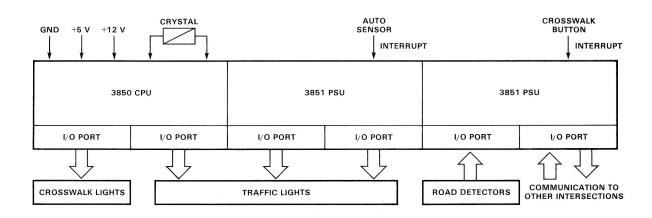


Fig. 2. Medium Complexity System

#### A MEMORY INTENSIVE SYSTEM

A typical application is a printing credit-verification terminal (Figure 3). Such a system requires high performance and yet must be low in cost if it is to reach a large market. Only four different F8 devices are required to handle a keyboard input, visual display, card reader, and printer as well as provide a

modem interface and memory interface for external RAM storage. This printing credit-verification system might be compared to a "bare mini-computer" in terms of utility, however, a detailed engineering evaluation would show that it costs less, has fewer parts and a more flexible I/O structure.

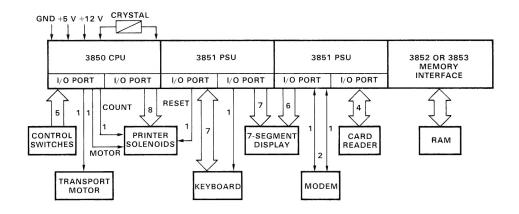


Fig. 3. Memory Intensive System

#### **MULTI-MICROPROCESSOR SYSTEM**

Figure 4 shows a specific application of the multi-processing concept as applied to a keyboard-to-floppy-disk system. Possibly this is the most cost-effective way of implementing this system, conservatively costing less than 50% of a conventional implementation. This system involves concurrent operation of three floppy disks, magnetic tape, CRT, keyboard, printer, and modem. While the low-speed devices (the keyboard, printer, and modem) can be adequately handled by the programmed I/O structure, the high-speed devices (disks, mag-

netic tape, and CRT) require separate F8 CPUs and PSUs.

This scheme provides simplicity of control, modularity, and freedom to expand. In this case, the units operating concurrently are: one magnetic-tape unit (25  $\mu$ s/byte); three floppy-disk units (32  $\mu$ s/byte each); and a CRT unit (71  $\mu$ s/byte). This combination requires an aggregate bandwidth of 0.1478 byte/ $\mu$ s. This is well within the F8's upper bandwidth limit of 0.5 byte/ $\mu$ s.

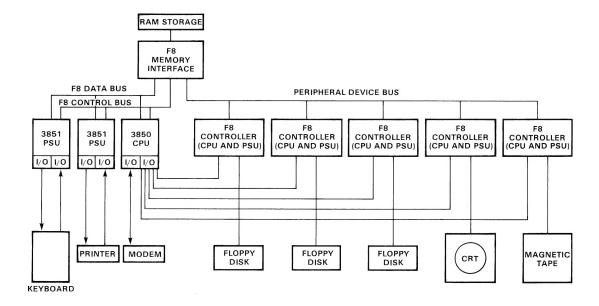


Fig. 4. Multi Microprocessor System



# **F8 CUSTOMER SUPPORT**

Fairchild's F8 system is supported by extensive hardware and software aids. F8 devices, standard RAMs, ROMs and PROMs are available now.

# **F8 DEVELOPMENT HARDWARE**

- F8M Development Module
  - The F8M offers a basic development system for micro-processor projects.
- F8S Development Module\*
  - This unit provides expanded capability for memory-intensive applications.
- F8C Microcomputer\*

The F8C is a complete microcomputer system including power supplies and control panel. I/O ports are brought out to connectors. The F8C is provided with a Native Assembler, Debug Package and Source Editor.

#### **F8 SOFTWARE**

Cross Assembler (FORTRAN IV)
 Accessible now on the G.E. and NCSS Timeshare Networks. Additional networks available as required.

\*Available soon.

Cross Simulator (FORTRAN IV)
 Accessible now on the same basis as Cross Assembler.

#### **F8 DOCUMENTATION**

- Microprocessor User's Manual
   The User's Manual provides device specifications, the instruction set in detail, and descriptions of the Cross Assembler and Simulator.
- Microprocessor Application Manual
   The Applications Manual provides initial details concerning bit manipulation, RAM expansion, extension of I/O ports, subroutines and boot strap loaders.

#### **F8 FIELD SUPPORT**

Training

A complete, hands-on, in-depth workshop to enable F8 users and potential users to design both hardware and software using the F8 microprocessor.

Field Application Engineers
Fairchild's knowledgeable FAEs will provide on-the-spot assistance with any F8 system application.

# **F8 INSTRUCTION SET SUMMARY**

The F8 instruction set contains over 60 different instructions which may be subdivided into 10 categories: Accumulator, Scratchpad Register, Indirect Scratchpad Address Register, Memory Reference, Data Counter, Status Register, Program Counter, Branch, Interrupt Control and Input/Output instructions. Because 55% of the F8 instructions are only one byte long, programs are short and memory requirements significantly reduced. An alphabetic listing of the instructions is shown below. The following pages contain a complete description of the F8 instructions, including the cycle time. Each cycle is 2  $\mu \rm s$  for a system with a 2 MHz clock frequency.

#### **F8 ADDRESSING MODES**

The F8 instruction set has eight modes of referencing either I/O, CPU registers or bulk memory.

Implied Addressing — The data for this one-byte instruction is implied by the actual instruction. For example, the POP instruction automatically implies that the content of the Program Counter will be set to the value contained in the Stack Register.

**Direct Addressing** — In these two-byte instructions, the address of the operand is contained in the second byte of the instruction. The Direct Addressing mode is used in the Input/Output class of instructions.

Short Immediate Addressing — Instructions whose addressing mode is Short Immediate have the instruction op code as the first four bits and the operand as the last four bits. They are all one-byte instructions.

**Long Immediate Addressing** — In these two-byte instructions, the first instruction byte is the op code and the second byte is the 8-bit operand.

**Direct Register Addressing** — This mode of addressing may be used to directly reference the Scratchpad Registers. By including the register number in the one-byte instruction, 12 of the 64 Scratchpad Registers may be referenced directly.

Indirect Register Addressing — All 64 Scratchpad Registers may be indirectly referenced, using the Indirect Scratchpad Register in the CPU. This 6-bit register, which acts as a pointer to the scratchpad memory, may either be incremented, decremented, or left unchanged while accessing the scratchpad register.

Indirect Memory Addressing — A 16-bit Indirect Address Register, the Data Counter, points to either data or constants in bulk memory. A group of one-byte instructions is provided to manipulate this area of memory. These instructions imply that the Data Counter is pointing to the desired memory byte. The Data Counter is self-incrementing, allowing for an entire data field to be scanned and manipulated without requiring special instructions to increment its content. The memory interface circuit contains two interchangeable data counters.

Relative Addressing — All F8 Branch Instructions use the relative addressing mode. Whenever a branch is taken, the Program Counter is updated by an 8-bit relative address contained in the second byte of the instruction. A branch may extend 128 locations forward or 127 locations back.

Logical AND Accumulator Immediate

#### ALPHABETIC LIST OF INSTRUCTIONS

ADC	Add Data Counter with Accumulator	DCI	Load Data Counter Immediate	NI	Logical AND Accumulator Immediate
ΑI	Add Immediate with Accumulator	DI	Disable Interrupt	NM	Logical AND Memory Accumulator
AM	Add Binary Accumulator with Memory	DS	Decrement Scratchpad Register	NOP	No Operation
AMD	Add Decimal Accumulator with Memory			NS	Logical AND Scratchpad and Accumulator
AS	Add Binary Accumulator with Scratchpad Register	El	Enable Interrupt		
ASD	Add Decimal Accumulator with Scratchpad Register			OI	Logical OR Immediate
		INC	Increment Accumulator	OM	Logical OR Memory with Accumulator
BC	Branch on Carry	IN	Input	OUT	Output
BF	Branch on False Condition	INS	Input Short	OUTS	Output Short
BM	Branch if Negative	INAD	Luman		
BNC	Branch if no Carry	JMP	Jump	PI	Push Program Counter into Stack Register
BNO	Branch if no Overflow	LI	Load Accumulator Immediate		Set Program Counter to New Location
BNZ	Branch if no Zero	LIS	Load Accumulator Short	PK	Push Program Counter into Stack Register
BP	Branch if Positive	LISL	Load ISAR – Lower 3 Bits		Set Program Counter from Scratchpad
BR	Absolute Branch	LISU	Load ISAR – Upper 3 Bits	POP	Put Stack Register into Program Counter
BR7	Branch if ISAR is not 7	LM	Load Memory		
BT	Branch on True Condition	LNK	Link Carry into Accumulator	SL	Shift Left
BZ	Branch on Zero Condition	LR	Load Register (5 Types)	SR	Shift Right
			Scratchpad		
CI	Compare Immediate		Program Counter	XDC	Exchange Data Counters
CLR	Clear Accumulator		ISAR	ΧI	Exclusive OR Immediate
CM	Compare with Memory		Status	XM	Exclusive OR Accumulator with Memory
COM	Complement Accumulator		Data Counter	XS	Exclusive OR Accumulator with Scratchpad

# ACCUMULATOR GROUP INSTRUCTIONS

OPERATION	MNEMONIC OP CODE	OPERAND	FUNCTION	MACHINE CODE	BYTES	CYCLES	OVF	STATU		
ADD CARRY	LNK	300	ACC→(ACC) + CRY	19	1	1	1/0	1/0	1/0	1/0
ADD IMMEDIATE	Al	ii	ACC <del>→</del> (ACC) + H'ii'	24ii	2	2.5	1/0	1/0	1/0	1/0
AND IMMEDIATE	NI	ii	ACC <del> (</del> ACC) ∧ H'ii'	21ii	2	2.5	0	1/0	0	1/0
CLEAR	CLR		ACC→H'00'	70	1	1	_	_	_	-
COMPARE IMMEDIATE	CI	ii	$H'ii' + (\overline{ACC}) + 1$	<b>25</b> ii	2	2.5	1/0	1/0	1/0	1/0
COMPLEMENT	сом		ACC <del></del> (ACC) ⊕ H'FF'	18	1	1	0	1/0	0	1/0
EXCLUSIVE-OR IMMEDIATE	ΧI	ii	ACC <del>~</del> (ACC) ⊕ H'ii'	23ii	2	2.5	0	1/0	0	1/0
INCREMENT	INC		ACC <del></del> (ACC) + 1	1F	1	1	1/0	1/0	1/0	1/0
LOAD IMMEDIATE	LI	ii	ACC <del>~</del> H′ii′	20ii	2	2.5	_	_	_	_
LOAD IMMEDIATE SHORT	LIS	i	ACC←H'0i'	7i	1	1	_	_	_	_
OR IMMEDIATE	OI	ii	ACC <del>~</del> (ACC) ∨ H'ii'	22ii	2	2.5	0	1/0	0	1/0
SHIFT LEFT ONE	SL	1	SHIFT LEFT 1	13	1	1	0	1/0	0	1/0
SHIFT LEFT FOUR	SL	4	SHIFT LEFT 4	15	1	1	0	1/0	0	1/0
SHIFT RIGHT ONE	SR	1	SHIFT RIGHT 1	12	1	1	0	1/0	0	1
SHIFT RIGHT FOUR	SR	4	SHIFT RIGHT 4	14	1	1	0	1/0	0	1

 $\textbf{BRANCH INSTRUCTIONS} \qquad \text{In all conditional branches PC}_0^{-\bullet}(\text{PC}_0) + 2 \text{ if the test condition is not met. Execution is complete in 3.0 cycles.}$ 

OPERATION	MNEMONIC OP CODE	OPERAND	FUNCTION	MACHINE CODE	BYTES	CYCLES	OVF	STATU		
BRANCH ON CARRY	ВС	aa	$PC_0 - [(PC_0) + 1] + H'aa' \text{ if } CRY = 1$	82aa	2	3.5	_	_	_	_
BRANCH ON POSITIVE	ВР	aa	$PC_0 \leftarrow [(PC_0) + 1] + H'aa' \text{ if SIGN} = 1$	81aa	2	3.5	_	_	-	_
BRANCH ON ZERO	BZ	aa	$PC_0 - [(PC_0) + 1] + H'aa' \text{ if ZERO} = 1$	84aa	2	3.5	-	_	-	_
BRANCH ON TRUE	ВТ	taa	$PC_0 \rightarrow [(PC_0) + 1] + H'aa'$ if any test is true $t = TEST CONDITION$ $\begin{array}{c cccc} \hline 2^2 & 2^1 & 2^0 \\ \hline ZERO & CRY & SIGN \end{array}$	8taa	2	3.5	-	_	_	-
BRANCH IF NEGATIVE	вм	aa	$PC_0^{-}[(PC_0) + 1] + H'aa' \text{ if } SIGN = 0$	91.aa	2	3.5	-	_	_	_
BRANCH IF NO CARRY	BNC	aa	$PC_{O} - [(PC_{O}) + 1] + H'aa' \text{ if } CARRY = 0$	92aa	2	3.5	-	_	-	_
BRANCH IF NO OVERFLOW	BNO	aa	$PC_{O} \leftarrow [(PC_{O}) + 1] + H'aa' \text{ if } OVF = 0$	98aa	2	3.5	~	_	-	_
BRANCH IF NOT ZERO	BNZ	aa	$PC_0 - [(PC_0) + 1] + H'aa' \text{ if ZERO} = 0$	94aa	2	3.5	_	_	-	
BRANCH IF FALSE TEST	BF	taa	$PC_{0} + [(PC_{0}) + 1] + H'aa' \text{ if all false test bits}$ $t = TEST \text{ CONDITION}$ $2^{3}  2^{2}  2^{1}  2^{0}$ $OVF  ZERO  CRY  SIGN$	9taa	2	3.5	-	-	-	-
BRANCH IF ISAR (LOWER) ≠ 7	BR7	aa	$PC_0 \rightarrow [PC_0] + 1] + H'aa' \text{ if } ISARL \neq 7$ $PC_0 \rightarrow [PC_0] + 2 \text{ if } ISARL = 7$	8Faa	2	2.5 2.0	_		_	_
BRANCH RELATIVE	BR	aa	$PC_{O} \rightarrow [(PC_{O}) + 1] + H'aa'$	90aa	2	3.5		_		-
JUMP*	JMP	aaaa	PC <sub>O</sub> H'aaaa'	29aaaa	3	5.5	_	_	_	_

# MEMORY REFERENCE INSTRUCTIONS In all Memory Reference Instructions, the Data Counter is incremented DC←DC + 1.

OPERATION	MNEMONIC OPERAND	D FUNCTION	MACHINE	BYTES	CYCLES		STATUS BITS		
OFERATION	OP CODE		CODE	Diles	CICLLS	OVF	ZERO	CRY	SIGN
ADD BINARY	AM	ACC→(ACC)+[(DC)]	88	1	2.5	1/0	1/0	1/0	1/0
ADD DECIMAL	AMD	ACC - (ACC) + [(DC)]	89	1	2.5	1/0	1/0	1/0	1/0
AND	NM	$ACC \leftarrow (ACC) \land [(DC)]$	8A	1	2.5	0	1/0	0	1/0
COMPARE	СМ	$[(DC)] + (\overline{ACC}) + 1$	8D	1	2.5	1/0	1/0	1/0	1/0
EXCLUSIVE OR	XM	$ACC - (ACC) \oplus [(DC)]$	8C	1	2.5	0	1/0	0	1/0
LOAD	LM	ACC→[(DC)]	16	1	2.5	_	_	_	_
LOGICAL OR	ОМ	$ACC \leftarrow (ACC) \lor [(DC)]$	8B	1	2.5	0	1/0	0	1/0
STORE	ST	(DC)→(ACC)	17	1	2.5	-	_	-	_

# ADDRESS REGISTER GROUP INSTRUCTIONS

OPERATION	MNEMONIC OP CODE	OPERAND	FUNCTION	MACHINE CODE	BYTES	CYCLES	OVF	STATU		S SIGN
ADD to DATA COUNTER	ADC		DC→(DC) + (ACC)	8E	1	2.5	_	-		-
CALL to SUBROUTINE*	PK.		$PC_0U \leftarrow (r12); PC_0L \leftarrow (r13); PC_1 \leftarrow (PC_0)$	ОС	1	4	-	-	-	_
CALL to SUBROUTINE IMMEDIATE	* PI	aaaa	PC <sub>1</sub> → (PC <sub>0</sub> ); PC <sub>0</sub> → H'aaaa	28aaaa	3	6.5	-	-	-	-
EXCHANGE DC	XDC		$DC_0 \stackrel{*}{\Rightarrow} DC_1$	2C	1	2	_	_	-	_
LOAD DATA COUNTER	LR	DC,Q	DCU <del>-(</del> (r14); DCL-(r15)	OF	1	4	-	_	-	_
LOAD DATA COUNTER	LR	DC,H	DCU <b>→</b> (r10); DCL <b>→</b> (r11)	10	1	4	-	-	-	-
LOAD DC IMMEDIATE	DCI	aaaa	DC <del> </del>	2Aaaaa	3	6	-	_	-	_
LOAD PROGRAM COUNTER	LR	PO,Q	PC <sub>0</sub> U→(r14); PC <sub>0</sub> L→(r15)	OD	1	4	-	_	-	_
LOAD STACK REGISTER	LR	P,K	PC <sub>1</sub> U <b>→</b> (r12); PC <sub>1</sub> L <b>→</b> (r13)	09	1	4	-	_	-	_
RETURN FROM SUBROUTINE*	POP		$PC_0 \leftarrow (PC_1)$	1C	1	2	_	_	_	_
STORE DATA COUNTER	LR	Q,DC	r14 <b>←</b> (DCU); r15 <b>←</b> (DCL)	OE	1	4	_	_	_	_
STORE DATA COUNTER	LR	H,DC	r10 <b>→</b> (DCU); r11 <b>→</b> (DCL)	11	1	4	_	_	_	_
STORE STACK REGISTER	LR	K,P	r12 <b>→</b> (PC <sub>1</sub> U); r13 <b>→</b> (PC <sub>1</sub> L)	08	1	4	-	_	-	_

# SCRATCHPAD REGISTER INSTRUCTIONS (Refer to Scratchpad Addressing Modes)

OPERATION	MNEMONIC	OPERAND	FUNCTION	MACHINE	BYTES	CYCLES		STATU		
	OP CODE		The second of the second second	CODE		1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	NA	ZERO		
ADD BINARY	AS	r	$ACC \leftarrow (ACC) + (r)$	Cr	1	1	1/0	1/0	1/0	1/0
ADD DECIMAL	ASD	r	$ACC \rightarrow (ACC) + (r)$	Dr	1	2	1/0	1/0	1/0	1/0
DECREMENT	DS	r	r <del>→</del> (r) + H'FF'	3r	1	1.5	1/0	1/0	1/0	1/0
LOAD	LR	A,r	ACC <del>→</del> (r)	4r	1	1	_	-	-	-
LOAD	LR	A,KU	ACC→(r12)	00	1	1	-	_	-	-
LOAD	LR	A,KL	ACC <del>→</del> (r13)	01	1	1	-	.—	-	-
LOAD	LR	A,QU	ACC→(r14)	02	1	1	-	_	-	_
LOAD	LR	A,QL	ACC←(r15)	03	1	1	_	-	-	-
LOAD	LR	r,A	r <b>→</b> (ACC)	5r	1	1	_	-	-	_
LOAD	LR	KU,A	r12 <del>-</del> (ACC)	04	1	1	-	_	_	_
LOAD	LR	KL,A	r13 <del>~</del> (ACC)	05	1	1	-	-	-	_
LOAD	LR	QU,A	r14 <del>←</del> (ACC)	06	1	1	-	-	-	_
LOAD	LR	QL,A	r15 <del>→</del> (ACC)	07	1	1	-	-	_	-
AND	NS	r	$ACC \leftarrow (ACC) \land (r)$	Fr	1	1	0	1/0	0	1/0
EXCLUSIVE OR	xs	r	ACC <del></del> (ACC) ⊕ (r)	Er	1	1	0	1/0	0	1/0

# **MISCELLANEOUS INSTRUCTIONS**

OPERATION	MNEMONIC	OPERAND	FUNCTION	MACHINE	BYTES	CYCLES		STATU		
O' EIIAII OI	OP CODE	Carta Carta		CODE	odrana i		OVF	ZERO	CRY	SIGN
DISABLE INTERRUPT	DI		RESET ICB	1A	1	2	-	_	_	-
ENABLE INTERRUPT*	El		SET ICB	1B	1	2	ettin	-	-	-
INPUT	IN	aa	ACC→(INPUT PORT aa)	26aa	2	4	0	1/0	0	1/0
INPUT SHORT	INS	а	ACC→(INPUT PORT a)	Aa	1	4***	0	1/0	Q	1/0
LOAD ISAR	LR	IS,A	ISAR →(ACC)	ОВ	1	1	_	-	-	_
LOAD ISAR LOWER	LISL	а	ISARL←a	1101a**	1	1	-	_		-
LOAD ISAR UPPER	LISU	а	ISARU→a	01100a**	1	1	-	-	_	-
LOAD STATUS REGISTER*	LR	U,W	W <b>→</b> (r9)	1D	1	2	1/0	1/0	1/0	1/0
NO-OPERATION	NOP		PC <sub>O</sub> →(PC <sub>O</sub> ) + 1	28	1	1	-	-	_	_
OUTPUT	OUT	aa	OUTPUT PORT aa←(ACC)	27aa	2	4	-	-	-	-
OUTPUT SHORT	OUTS	а	OUTPUT PORT a→(ACC)	Ва	1	4***	-	-	-	-
STORE ISAR	LR	A,IS	ACC→(ISAR)	OA	1	1	-	_	-	-
STORE STATUS REG	LR	J,W	r9 <b>→</b> (W)	16	1	1	-	_	_	_

# **NOTES**

Each lower case character represents a Hexadecimal digit Each cycle equals 4 machine clock periods Lower case denotes variables specified by programmer

#### **Function Definitions**

<b>←</b>	is replaced by
()	the contents of
<b>( - )</b>	Binary "1"s complement of
+	Arithmetic Add (Binary or Decimal)
<b>⊕</b>	Logical "OR" exclusive
٨	Logical "AND"

Logical "OR" inclusive Hexadecimal digit

#### Register Names

а	Address Variable
Α	Accumulator
DC	Data Counter (Indirect Address Register)
DCO	Data Counter #0 (Indirect Address Register #0)
DC <sub>1</sub>	Data Counter #1 (Indirect Address Register #1)
DCĹ	Least significant 8 bits of Data Counter Addressed
DCU	Most significant 8 bits of Data Counter Addressed
Н	Scratchpad Register #10 and #11
i and ii	immediate operand
ICB	Interrupt Control Bit
IS	Indirect Scratchpad Address Register
ISAR	Indirect Scratchpad Address Register
ISARL	Least Significant 3 bits of ISAR
ISARU	Most Significant 3 bits of ISAR
J	Scratchpad Register #9

K	Registers #12 and #13
KL	Register #13
KU	Register #12
PCO	Program Counter
PCOL	Least Significant 8 bits of Program Counter
PCOU	Most Significant 8 bits of Program Counter
PC <sub>1</sub>	Stack Register
PC <sub>1</sub> L	Least Significant 8 bits of Program Counter
PC <sub>1</sub> U	Most Significant 8 bits of Active Stack Register
a '	Registers #14 and #15
QL	Register #15
QU	Register #14
r	Scratchpad Register (any address thru 11)
W	Status Register

# Scratchpad Addressing Modes (Machine Code Format)

$\mathbf{r} = \mathbf{C}$	(Hexadecimal), Register Addressed by ISAR (Unmodified)
r = D	(Hexadecimal), Register Addressed by ISAR; ISARL Incremented
r = E	(Hexadecimal). Register Addressed by ISAR; ISARL Decremented
r = F	(No operation performed)
r = 0	(Hexadecimal), Register 0 thru 11 addressed directly from
thru B	the Instruction

Status f	Status Register						
-	No change in condition						
1/0	is set to "1" or "0" depending on conditions						
CRY	Carry Flag						
OVF	Overflow Flag						
SIGN	Sign of Result Flag						
ZERO	Zero Flag						

<sup>\*</sup>Privileged instruction

<sup>\*\*3-</sup>bit octal digit

<sup>\*\*\*2</sup> machine cycles for CPU ports

**POWER REQUIREMENTS:**  $V_{DD} = +5.0 \text{ V} \pm 5\%; V_{GG} = +12.0 \text{ V} \pm 5\%; V_{SS}^{1} = 0 \text{ V}; T_{A} = 0^{\circ}\text{C to } 70^{\circ}\text{C}; f = 2 \text{ MHz}$ 

PART TYPE	SYMBOL	PARAMETER	TYP	MAX	UNITS	TEST CONDITIONS (Outputs Unloaded)
3850	I <sub>DD</sub>	V <sub>DD</sub> Current V <sub>GG</sub> Current	30 15	80 25	mA mA	2 MHz
3851	I <sub>DD</sub> I <sub>GG</sub>	V <sub>DD</sub> Current V <sub>GG</sub> Current	30 10	70 18	mA mA	2 MHz
3852 3853	I <sub>DD</sub> I <sub>GG</sub>	V <sub>DD</sub> Current V <sub>GG</sub> Current	35 13	70 30	mA mA	2 MHz
3854	I <sub>DD</sub> I <sub>GG</sub>	V <sub>DD</sub> Current V <sub>GG</sub> Current	20 15	40 28	mA mA	2 MHz

# SIGNAL ELECTRICAL

**SPECIFICATIONS** :  $V_{DD} = +5.0 \text{ V} \pm 5\%$ ;  $V_{GG} = +12.0 \text{ V} \pm 5\%$ ;  $V_{SS} = 0 \text{ V}$ ;  $T_{A} = 0^{\circ}\text{C}$  to  $70^{\circ}\text{C}$ ; f = 2 MHz

SIGNAL NAME (NUMBER, TYPE)	SOURCE OR RECEIVING DEVICE	V <sub>OH</sub> MIN	$V_{IH}$ MIN	V <sub>OL</sub> MAX	V <sub>IL</sub> MAX	LOAD
DATA BUS (8 INPUTS/ OUTPUTS)	3850 3851 3852/3 3854	3.9	3.5	0.4	0.8	100 pF I <sub>SOURCE</sub> = -100 μA I <sub>SINK</sub> = 900 μA
CONTROL BUS (5 OUTPUTS)	3850	3.9		0.4		$I_{SOURCE} = -100 \mu A$
CONTROL BUS 5 INPUTS)1	3851 3852/3		3.5		0.8	
/O PORTS 16 INPUTS/OUTPUTS)	3850 3851	2.9 (1 TTL) 3.9 (unloaded)	3.52	0.4	0.8	100 pF plus 1 H-TTL Load
CLOCK REFERENCE (INPUT)	3850		4.0		0.8	
SYSTEM CLOCKS PHI AND WRITE OUTPUTS)	3850	4.4		0.4		$100 \text{ pF, } I_{\text{SINK}} = 900 \mu\text{A}$ $I_{\text{SOURCE}} = -100 \mu\text{A}$
SYSTEM CLOCKS (PHI AND WRITE INPUTS)	3851 3852/3 3854		4.0		0.8	
RESET (INPUT)	3850		3.52		0.8	$I_{IL} = 0.3$ mA Max at $V_{IN} = V_{SS}$
NTERRUPT CONTROL BIT OUTPUT)	3850	3.9		0.4		50 pF plus 100 μA ISOURCE <sup>or I</sup> SINK
INTERRUPT REQUEST (INPUT)	3850		3.52		0.8	$I_{\text{IL}} = 1 \text{ mA Max at V}_{\text{IN}} = 0.4$
INTERRUPT REQUEST (OUTPUT)	3851 3853	OPEN DRAIN		0.4		100 pF plus I <sub>SINK</sub> = 1 mA
EXTERNAL INTERRUPT (INPUT)	3851 3853		3.5		1.2	
PRIORITY IN (INPUT)	3851 3853		3.5		0.8	
PRIORITY OUT (OUTPUT)	3851	3.9	-	0.4		50 pF plus 100 μA ISOURCE <sup>or I</sup> SINK
DBDR (OUTPUT)	3851	OPEN DRAIN <sup>3</sup>		0.4		100 pF plus I <sub>SINK</sub> = 2.5 mA
ADDRESS LINES and RAM WRITE (16 OUTPUTS)	3852/3 3854	4.0		0.4		500 pF plus 2 TTL Loads
REGDR (INPUT/OUTPUT)	3852/3	3.9	3.5	0.4	0.8	100 pF plus 1 H-TTL Load
CPU READ (OUTPUT)	3852/3	3.9		0.4		50 pF plus 1 H-TTL Load
MEM IDLE, CYCLE REO and CPU SLOT (OUTPUTS)	3852	3.9		0.4		50 pF plus 1 H-TTL Load
MEM IDLE (INPUT)	3854		3.5		0.8	
ENABLE, DIRECTION, TRANSFER, DMA WRITE SLOT, STROBE (OUTPUTS)	3854	3.9		0.4		50 pF plus 1 H-TTL Load
XFER REQ, P1,P2 (INPUTS)	3854		3.5		0.8	
LOAD REG, READ REG (INPUTS)	3854		3.5		0.8	

 $<sup>^{1}</sup>$ 3854 receives two control signals from external decoding device.  $^{2}$ Internal pull-up resistor to  $V_{DD}$ .  $^{3}$ External pull-up resistor required.

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